

**Amendments to the Abstract:**

**The Abstract, at page 26, is to be amended as follows:**

**Abstract**

A robot is provided which is adapted to operate in association with an interface surface ~~having, which~~ has disposed therein or thereon coded data indicative of an identity of the interface surface and of a plurality of reference points of the interface surface~~[[, the]].~~ The robot comprising: ~~(1)~~ has movement means to allow the robot to move over the interface surface~~[[;(2)]]~~, a sensing device which senses at least some of the coded data and generates indicating data indicative of the identity of the interface surface and of a position of the robot on the interface surface~~[[; (3)]]~~, and communication means to~~[[;(A)]]~~ transmit the indicating data to a computer system, ~~the computer system which is~~ programmed to select and execute a computer application based on at least the identity of the interface surface; ~~and, (B), and to~~ receive movement instructions from the selected computer application, ~~whereby, the.~~ The behaviour of the robot is at least in part controlled by the selected computer application.